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Lalitha Pakala

# Kalman Filtering for Mitigation of Optical Fiber Transmission Impairments



FRIEDRICH-ALEXANDER UNIVERSITÄT ERLANGEN-NÜRNBERG



# Kalman Filtering for Mitigation of Optical Fiber Transmission Impairments

# Kalman Filterung zur Unterdrückung von Störeinflüssen bei der faseroptischen Übertragung

Der Technischen Fakultät der Friedrich-Alexander-Universität Erlangen-Nürnberg zur Erlangung des Doktorgrades

### Doktor-Ingenieur (Dr.-Ing.)

vorgelegt von

### Lalitha Pakala

aus Nellore

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#### Abstract

Coherent optical communication systems offer great capability to transmit high data throughput, in order to accommodate the ever increasing data traffic. The advent of coherent detection aided with digital signal processing (DSP) has been one of the major technology breakthroughs that made it possible to multiply the spectral efficiency several times and also to compensate the fiber transmission impairments electronically. However, the nonlinear Kerr effect and its interplay with the amplified spontaneous emission (ASE) noise resulting in the nonlinear phase noise (NLPN), are still a bottleneck restricting the maximum possible transmission reach and capacity. In addition, equalization of the polarization effects as well as the phase and frequency offsets between the transmitter laser and the local oscillator (LO) is also crucial when employing higher order modulation formats and multiplexing techniques. Therefore, efficient DSP algorithms are under active research over the past decade.

In this thesis, the potential of Kalman filtering is exploited for the joint mitigation of several optical transmission impairments including laser phase noise, fiber nonlinearity, amplitude noise, frequency offset as well as polarization effects. A carrier phase and amplitude noise estimation (CPANE) algorithm is proposed and implemented using an extended Kalman filter (EKF) that estimates a complex quantity to track the phase and amplitude noise, simultaneously. Although, various DSP algorithms have been studied in this thesis, more emphasis will be given to the EKF-CPANE algorithm. Its performance is investigated in detail and compared to the conventional DSP algorithms. Approaches to enhance the nonlinear tolerance of the EKF-CPANE algorithm by incorporating with the existing techniques like digital backward propagation (DBP) will be presented. A two stage EKF approach is introduced that exhibits an improved tolerance towards phase and frequency offsets. Furthermore, an adaptive and cascaded Kalman filtering (CKF) is proposed for the joint tracking of polarization state and phase noise. A brief analysis on incorporating forward error correction (FEC) with the EKF-CPANE algorithm is also discussed. Extensive numerical investigations prove that the Kalman filters offer an attractive solution to jointly compensate several optical transmission impairments and thereby, enhance the transmission performance. Moreover, owing to their real-time feasibility and low complexity, Kalman filters seem to be a promising component of future coherent receivers.

### Zusammenfassung

Kohärente optische Übertragungsssysteme bieten die Möglichkeit eines hohen Datendurchsatzes und damit auch das Potenzial, dem ständig wachsenden Datenverkehr gerecht zu werden. Das Aufkommen kohärenter Detektion in Verbindung mit der digitalen Signalverarbeitung (DSP) war einer der wichtigsten technologischen Durchbrüche, die es möglich gemacht haben, die spektrale Effizienz zu vervielfachen und auch die Störeinflüsse bei der Faserübertragung elektronisch zu kompensieren. Der nichtlineare Kerr-Effekt und sein Zusammenspiel mit dem Rauschen der verstärkten spontanen Emission (ASE), das zu dem nichtlinearen Phasenrauschen (NLPN) führt, sind jedoch immer noch ein Faktor, der die maximal mögliche Übertragungsreichweite und-kapazität einschränkt. Zusätzlich ist ein Ausgleich der Polarisationseffekte sowie der Phasen- und Frequenzversätze zwischen dem Senderlaser und dem lokalen Oszillator (LO) entscheidend, wenn Modulationsformate höherer Ordnung und Multiplextechniken verwendet werden. Daher wurden effiziente DSP Algorithmen in der letzten Dekade aktiv erforscht.

In dieser Arbeit wird das Potenzial der Kalman Filterung zur gemeinsamen Abschwächung mehrerer Beeinträchtigungen bei der optischen Übertragung, einschliesslich Laserphasenrauschen, Faser Nichtlinearität, Amplitudenrauschen, Frequenzversatz sowie Polarisationseffekte genutzt. Ein Algorithmus zur Trägerphasen und Amplitudenrauschschätzung (CPANE) wird vorgeschlagen und implementiert. Dabei wird ein erweitertes Kalman Filters (EKF) eingesetzt, das eine komplexe Grösse schätzt, um die Phase und Amplitudenrauschen gleichzeitig zu verfolgen. Obwohl in dieser Arbeit verschiedene DSP-Algorithmen untersucht wurden, wird der EKF-CPANE Algorithmus stärker betont. Seine Leistung wird detailliert untersucht und mit den herkömmlichen DSP-Algorithmen verglichen. Ansätze zur Verbesserung der nichtlinearen Toleranz des EKF-CPANE Algorithmus durch Integration in bestehende Techniken wie die digitale Rückwärtspropagation (DBP) werden vorgestellt. Ein zweistufiger EKF-Ansatz wird eingeführt, der eine verbesserte Toleranz gegenüber Phasen- und Frequenzversätzen aufweist. Darüber hinaus wird eine adaptive und kaskadierte Kalman-Filterung (CKF) zur gemeinsamen Verfolgung von Polarisationszustand und Phasenrauschen vorgeschlagen. Eine kurze Analyse zur Integration einer Vorwärtsfehlerkorrektur (FEC) mit dem EKF-CPANE Algorithmus wird ebenfalls diskutiert. Umfangreiche numerische Untersuchungen belegen, dass die Kalman Filter eine attraktive Lösung bieten, um verschiedene störende Effekte bei der optischen Übertragung gemeinsam zu kompensieren und dadurch die Übertragungsleistung zu verbessern. Aufgrund ihrer geringen Komplexität und Umsetzbarkeit in Echtzeit scheinen Kalman Filter eine vielversprechende Komponente zukünftiger kohärente Empfängerkonzepte zu sein.

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V

Lalitha Pakala, October 2018

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## **List of Abbreviations**

| ACF     | Auto correlation function   |
|---------|---|
| A-CKF   | Adaptive cascaded Kalman filtering  |
| ADC     | Analog to digital converter   |
| AKF     | Adaptive Kalman filtering   |
| AO      | Amplitude dependent optimization  |
| AO-CDBP | Amplitude dependent optimization of correlated digital backward propagation |
| ASE     | Amplified spontaneous emission  |
| A-SSFM  | Asymmetric split step Fourier method  |
| AWGN    | Additive white Gaussian noise   |
| BP      | Backward propagation  |
| BTB     | Back-to-back  |
| CA      | Code aided  |
| CA-EKF  | Code aided extended Kalman filtering  |
| CD      | Chromatic dispersion  |
| CDBP    | Correlated digital backward propagation                                     |
| CKF     | Cascaded Kalman filtering   |
| СМА     | Constant modulus algorithm  |
| CPE     | Carrier phase estimation  |
| CPANE   | Carrier phase and amplitude noise estimation                                |
| CW      | Continuous wave   |
| DBP     | Digital backward propagation  |
| DBPSK   | Differential binary phase shift keying                                      |
| DCF     | Dispersion compensating fiber   |
| DD      | Decision directed   |
| DD-CPE  | Decision directed carrier phase estimation                                  |
| DD-PLL  | Decision directed phase locked loop   |
| DGD     | Differential group delay  |
| DQPSK   | Differential quadrature phase shift keying                                  |
| DSP     | Digital signal processing   |

| XII       |  |
|-----------|--|
| EDFA      | Erbium doped fiber amplifier   |
| EKF       | Extended Kalman filter   |
| EKF-CPANE | Extended Kalman filter-carrier phase and ampli-<br>tude noise estimation |
| FDE       | Frequency domain equalization  |
| FEC       | Forward error correction   |
| FFT       | Fast Fourier transformation  |
|           |  |

| FDE        | Frequency domain equalization                       |
|------------|---|
| FEC        | Forward error correction                            |
| FFT        | Fast Fourier transformation                         |
| FIR        | Finite impulse response                             |
| FO         | Frequency offset                                    |
| FOE        | Frequency offset estimation                         |
| GVD        | Group velocity dispersion                           |
| IDD-CPE    | Ideal decision directed CPE                         |
| IDD-PLL    | Ideal decision directed PLL                         |
| IEKF-CPANE | Ideal extended Kalman filtering CPANE               |
| IFFT       | Inverse fast Fourier transformation                 |
| IIR        | Infinite impulse response                           |
| IMP-DD-CPE | Improved decision directed carrier phase estimation |
| КМС        | K-means clustering                                  |
| LKF        | Linear Kalman Filter                                |
| LO         | Local oscillator                                    |
| LPF        | Low pass filter                                     |
| MIMO       | Multiple input multiple output                      |
| ML         | Maximum likelihood                                  |
| MLSE       | Maximum likelihood sequence estimation              |
| MMA        | Multi modulus algorithm                             |
| MMSE       | Minimum mean squared error                          |
| MW         | Measurement weight                                  |
| MZM        | Machzehnder modulator                               |
| NDD        | Non decision directed                               |
| NLPN       | Nonlinear phase noise                               |
| NLSE       | Nonlinear Schroedinger equation                     |
| NZ-DSF     | Nonzero dispersion shifted fiber                    |
| OBPF       | Optical band pass filter                            |
| ODBP       | Optimized digital backward propagation              |
| OOK        | On off keying                                       |

| OSNR     | Optical signal to noise ratio                                  |
|----------|--|
| OSPS     | One step per span  |
| PBC      | Polarization beam combiner                                     |
| PBS      | Polarization beam splitter                                     |
| PDM / PM | polarization division multiplexing / Polarization multiplexing |
| PLL      | Phase locked loop  |
| PMD      | Polarization mode dispersion                                   |
| PSK      | Phase shift keying   |
| QAM      | Quadrature amplitude modulation                                |
| QPSK     | Quadrature phase shift keying                                  |
| SD-FEC   | Soft decision forward error correction                         |
| SPM      | Self phase modulation  |
| SMF      | Single mode fiber  |
| SSMF     | Standard single mode fiber                                     |
| SSFM     | Split step Fourier method                                      |
| SSM      | State space model  |
| SSNL     | Single step nonlinear  |
| S-SSFM   | Symmetric split step Fourier method                            |
| U-CPE    | Universal CPE  |
| UKF      | Unscented Kalman filter  |
| VV       | Viterbi-Viterbi  |
| VV-CPE   | Viterbi-Viterbi carrier phase estimation                       |
| WDM      | Wavelength division multiplexing                               |
| WIA      | Weighted innovation approach                                   |
| XPM      | cross phase modulation   |

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