Nonlinear State and Parameter Estimation for Small Unmanned Aircraft Systems

A thesis accepted by the Faculty of Aerospace Engineering and Geodesy of the University of Stuttgart in partial fulfillment of the requirements for the degree of Doctor of Engineering Sciences (Dr.-Ing.)

by

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Date of Defense: December 17, 2015

Institute of Flight Mechanics and Control University of Stuttgart 2016

Fortschrittsberichte des Instituts für Flugmechanik und Flugregelung

Band 6

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Nonlinear State and Parameter Estimation for Small Unmanned Aircraft Systems

D 93 (Diss. Universität Stuttgart)

Shaker Verlag Aachen 2016

Bibliographic information published by the Deutsche Nationalbibliothek

The Deutsche Nationalbibliothek lists this publication in the Deutsche Nationalbibliografie; detailed bibliographic data are available in the Internet at http://dnb.d-nb.de.

Zugl.: Stuttgart, Univ., Diss., 2015

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Printed in Germany.

ISBN 978-3-8440-4281-8 ISSN 2199-3483

Shaker Verlag GmbH • P.O. BOX 101818 • D-52018 Aachen Phone: 0049/2407/9596-0 • Telefax: 0049/2407/9596-9

Internet: www.shaker.de • e-mail: info@shaker.de

To Lea!

Preface

When I started working at the Institute of Flight Mechanics and Control, there was nothing but the basic idea to establish an sUAS research group with a strong focus on real world demonstrations. As we started from scratch, I spend much time in building up an adequate development environment and learned a lot on digital circuits, PCB design, and soldering. Although this was quite enjoying, it did not bring me any closer to serious research contributions. At some point in time, I even was not sure if I would ever submit a thesis, and now it is hard for me to believe that I managed to get that far.

First of all, I would like to thank my supervisor Walter Fichter. All that would not have been possible without his excellent guidance and support. Besides the fruitful technical discussions he always encouraged me to carry on. Moreover, many thanks to Eric N. Johnson for taking the responsibility of acting as coreferee of this work. It was a real honor that he made all the way from Atlanta, Georgia to Stuttgart to join my defense.

Furthermore, I would like to thank the staff at the Institute of Flight Mechanics and Control for the wonderful time I had. It was a really pleasant working atmosphere and I enjoyed it a lot! My special thanks go to André Posch and Michael Frangenberg for their great commitment in the hardware and software development of the onboard computing system. Both of them contributed significantly to the numerous successful flight tests both in the scope of this thesis and for several other projects.

Last but not least I want to thank my wife Gisela and my daughter Lea for their endless patience and encouragement. You two are the most important thing in my life.

Stuttgart, February 2016 Florian Weimer

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