

Cooperation and Coordination of Constraint Solvers

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Zusammenfassung

Deklarativen Programmiersprachen liegt die Idee zugrunde, daß die Formulierung von Programmen nah an der Problemspezifikation und -domain möglich sein sollte. Programme deklarativer Sprachen bestehen meist aus mathematischen Objekten, d.h. Relationen und Funktionen. Dementsprechend unterscheidet man deklarative Programmiersprachen gewöhnlich in logische, funktionale, funktional-logische und Constraint-Programmiersprachen.

Constraint-Programmierung ist eine relativ junge Entwicklung auf dem Gebiet deklarativer Sprachen. Gleichwohl gibt es inzwischen eine große Menge von Constraint-Programmiersprachen, ebenso wurden viele Constraint-Lösungsmechanismen ausführlich untersucht. In der Constraint-Programmierung werden Probleme mittels Constraints spezifiziert. Ein Constraint, zu deutsch Bedingung oder Einschränkung, ist dabei eine Formel, die Eigenschaften von Objekten oder Beziehungen zwischen diesen ausdrückt. Programme, in denen Probleme mittels Constraints beschrieben sind, können mit sog. Constraint-Lösern behandelt werden. Das sind Algorithmen die auf Probleme spezieller Bereiche, d.h. spezieller Domains, anwendbar sind. Constraint-Löser erlauben meist, Constraints auf Erfüllbarkeit zu testen, d.h. sie zu lösen, sie erlauben, das Enthalten von Constraints in anderen zu prüfen und, teilweise sogar, passende Variablenzuweisungen zu finden, so daß die Constraints, die das Problem beschreiben, erfüllt sind.

Obwohl das Paradigma der Constraint-Programmierung effiziente Mechanismen zur Behandlung von Constraints vieler Domains anbietet, kann ein Constraint-Löser gewöhnlich nur Constraints seiner ganz speziellen Domain behandeln. Daher ist es oft wünschenswert und es wäre vorteilhaft, Constraint-Systeme kombinieren und die entsprechenden Constraint-Lösungs-Mechanismen kooperieren lassen zu können, weil damit die Behandlung und Lösung von Problemen möglich wird, die jeweils einzelne Constraint-Löser nicht behandeln können.

In dieser Arbeit stellen wir ein allgemeines Schema für die Kooperation von Constraint-Lösern vor. Die Basis unseres Systems ist dabei eine einheitliche Schnittstelle für Constraint-Löser, die eine fein-granulare for-

male Spezifikation des Informationsaustausches zwischen Constraint-Lösern erlaubt. Darauf aufbauend entwickeln wir einen offenen und sehr flexiblen Kombinationsmechanismus für Constraint-Löser. Wir bezeichnen diesen Kombinationsmechanismus als offen, da er eine einfache Integration von Constraint-Lösern in das Gesamtsystem unabhängig von ihrer Domain und Implementierungssprache erlaubt. Der Kombinationsmechanismus ist flexibel, da er die Definition vieler verschiedener Kooperationsstrategien der integrierten Löser in einfacher Weise ermöglicht.

Wir schlagen einen allgemeinen Rahmen für die Definition des Verhaltens eines Systems kooperierender Constraint-Löser vor und zeigen seine Verwendung für die schrittweise Definition von Reduktionssystemen, die Kooperationsstrategien eines solchen Systems beschreiben. Die Modularität unserer Definitionen von Reduktionsrelationen auf verschiedenen Ebenen erlaubt, entsprechend der aktuellen Situation und Ressourcen eine große Anzahl von Kooperationsstrategien für die Löser zu definieren, so daß unser Gesamtsystem ein allgemeines Framework für kooperierende Constraint-Löser darstellt.

Abstract

Declarative programming languages base on the idea that programs should be as close as possible to the problem specification and domain. Programs of these languages usually consist of directly formulated mathematical objects, i.e. relations and functions. Accordingly, declarative languages are distinguished into logic, functional, functional-logic, and constraint programming languages.

Even if constraint programming is a young development in declarative programming languages, meanwhile, there is a wide range of constraint programming languages, and many domains and associated constraint solving mechanisms have been investigated. Using constraint programming, problems are specified by means of constraints. A constraint is usually a first order formula which describes properties of objects or relations between them. Problems described by constraints are handled by constraint solvers, i.e. specific algorithms for particular domains which mostly allow to check satisfiability of constraints, i.e. to solve constraints, to compute entailed constraints, and even to find variable assignments such that the constraints specifying the problem are satisfied.

Though the paradigm of constraint programming offers efficient mechanisms to handle constraints of various domains, one constraint solver can only handle constraints of a particular constraint system. Thus, it is often desirable and advantageous to combine several constraint systems and the associated constraint solving techniques because this combination makes it possible to solve problems that none of the single solvers can handle alone.

In this work, we propose a general scheme for the cooperation of constraint solvers. The base of our system is a uniform interface for constraint solvers which allows a fine-grain formal specification of information exchange between constraint solvers. On top of this interface, we develop an open and flexible combination mechanism for constraint solvers. The combination is open in the sense that whenever a new constraint system with associated constraint solver (satisfying certain properties) arises, it can be easily incorporated into the overall system independently of its domain and the language in which the constraint solver is implemented. It is flexible because

the definition of different strategies for the cooperation of the single solvers is possible in a simple way.

We propose a general frame for the definition of the behaviour of a system of cooperating constraint solvers. Using this frame, we develop in a step-wise fashion reduction systems which describe strategies of such an overall system of cooperating solvers. The modularity of our definitions of reduction relations at different levels allows to define a wide range of cooperation strategies for the solvers according to the current situation, resources, and requirements such that our overall system forms a general framework for cooperating solvers.

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x

Contents

1	Introduction	1
2	Predicate Logic	7
2.1	Signatures and Structures	7
2.2	Terms, Formulae, and Validity	8
3	Constraint Programming	13
3.1	Constraint Systems and Solvers	13
3.2	Finite Domain Constraints	20
3.3	A Uniform Interface for Constraint Solvers	23
4	Cooperating Constraint Solvers	39
4.1	Preliminaries	39
4.2	Flattening Disjunctive Constraints	43
4.3	The Architecture	52
4.4	Description of the System Behaviour	54
4.4.1	(Overall) Configurations	54
4.4.2	Basic Relations	55
4.4.3	Reduction of Overall Configurations	60
4.5	Computation Results	63
4.5.1	Results of Derivations	64
4.5.2	Comparison of Solution Sets	74
4.5.3	Computing Solutions	88
4.6	Extension of Constraint Solvers	91
5	Coordination of Constraint Solvers: Strategies	95
5.1	How to Define a Strategy	96
5.2	The Production Level	98
5.2.1	Single Propagation – Single Projection	99
5.2.2	Multiple Propagation – Single Projection	101
5.2.3	Multiple Propagation – Multiple Projection	102

5.2.4	Comparison at Production Level	109
5.3	The Application Level	111
5.3.1	Simplification Rules	111
5.3.2	Sequential Reduction of Configurations	111
5.3.3	Parallel Reduction of Configurations	112
5.4	Reduction Systems for Overall Configurations	113
5.4.1	Comparison of Reduction Systems	114
5.5	Application of Regulation Mechanisms	117
5.5.1	Choosing Constraint Systems	118
5.5.2	Choosing Constraints	120
5.6	Computation Results	120
5.6.1	Results of Derivations	121
5.6.2	Comparison of Solution Sets	123
5.7	Dependencies	123
6	Implementation	127
6.1	Integrated Constraint Solvers	128
6.2	Cooperation	132
6.3	Configuration of the System	135
6.4	Discussion	139
7	Conclusion and Related Work	141
7.1	Summary and Contributions	141
7.2	Related Work	143
7.3	Future Work	154
A	Example	155
B	Fundamentals	163
C	Termination	165
D	Confluence	183
E	Further Proofs	191

List of Figures

1.1	An electric circuit	3
3.1	$(y \leq 4x) \wedge (x \leq 4y)$	18
3.2	$(4y < x) \wedge (4x < y) \wedge (0 < x + y)$	19
3.3	A graph representing the CSP of Example 3.2.2	21
3.4	A graph representing \mathcal{CSP}'	23
3.5	Constraint solver CS_ν with constraint store C^ν and interface .	24
3.6	Interface function <i>tell</i> , first version	25
3.7	Interface function <i>tell</i> (requirements), second version	27
3.8	Interface function <i>tell</i> (requirements), final version	28
3.9	Propagating a redundant constraint c	28
3.10	Propagating a constraint c	29
3.11	Propagating a contradictory constraint c	29
3.12	A possible <i>tell</i> definition for complete constraint solvers with total entailment check	30
3.13	Function <i>proj</i> (requirements)	35
3.14	Projection of a constraint store	35
3.15	Interface function $proj_{\nu \rightarrow \mu}$ (requirements)	36
3.16	Constraint solver CS_ν with detailed interface	37
4.1	<i>Flatten</i> : Transformation of a mixed disjunctive constraint into a pure disjunctive constraint.	45
4.2	Architecture of the overall system	53
4.3	$prop \subseteq \bigcup_{q \in L} Cons_q \times \Xi \times \Xi$	57
4.4	Changes of tag t_q by <i>prop</i>	58
4.5	$put_proj \subseteq L \times \mathcal{P}(L \times \mathcal{P}(\mathcal{P}(X))) \times \Xi \times \Xi$	59
4.6	Changes of tag t_q by <i>prop</i> and <i>put_proj</i>	60
5.1	Information exchange of cooperating solvers according to Example 1.0.1	97
5.2	Behaviour of $CS_{3_{\text{Ex}}}$ propagating c_{11} and c_{12} by two successive $\xrightarrow{\text{sub}_3}_{\text{Ex}}$ steps	100

5.3	Behaviour of $CS_{3\text{Ex}}$ propagating c_{11} and c_{12} by one derivation step	$\xrightarrow[+]^{sub}_{+} 3_{\text{Ex}}$ 102
5.4	Information exchange handling the input constraint conjunction using \xrightarrow{sub}_{par}	108
6.1	The fixed cooperation strategy	133
6.2	Input-file: The electric circuit	137
6.3	The SEND-MORE-MONEY problem	138
6.4	Input-file: SEND-MORE-MONEY	139
C.1	Derivation tree T of configuration \mathcal{G}_i	168
C.2	Tree T' of constraints occurring in a derivation sequence	171
E.1	Implication relation between formulae	192