

NLoS Localization and UWB Channel Capacity Analysis

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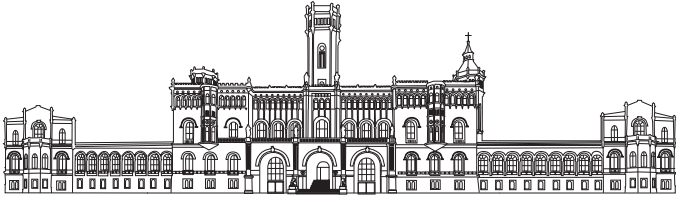
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Leibniz
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KURZFASSUNG

Die vorliegende Dissertation hat die Lokalisierung und Kommunikation mittels Funk zum zentralen Inhalt: zum einen wird, basierend auf der Ankunftszeit (Time of Arrival, ToA) eines gesendeten Funksignals, die Position einer Mobilstation geschätzt und die Genauigkeit der Schätzung beurteilt. Zum anderen wird die Kanalkapazität von ultrabreitbandigen Mehrantennen-Nachrichtenkanälen berechnet um qualitative Aussagen über die erzielbare Datenrate zu gewinnen.

Im ersten Teil der Arbeit wird eine klassische ToA-Schätzmethode zusammen mit einem Pfadverlustmodell betrachtet. Es wird gezeigt, dass die Berücksichtigung der Pfadverluste die Genauigkeit der ToA-Schätzung erhöht unter der Voraussetzung, dass der Pfadverlustexponent (Path Loss Exponent, PLE) am Empfänger perfekt bekannt ist. Ausgehend von der sich ergebenden Leistungsverbesserung der ToA-Schätzung wird als konsequenter nachfolgender Schritt die *nicht perfekte* Kenntnis des PLEs am Empfänger untersucht. Hier zeigt sich, dass der Maximum-Likelihood-Schätzer (ML-Schätzer) von einer geringen deterministischen PLE-Störung bei einem kleinen Signal-zu-Rausch-Verhältnis (Signal-to-Noise-Ratio, SNR) profitiert. Weiterhin ergibt sich für die ML-Schätzung im Falle des nicht perfekten PLE ein kleinerer mittlerer quadratischer Fehler im Vergleich zum konventionellen Maximum-Correlation-Schätzer (MC-Schätzer), der keinerlei PLE-Kennntnis annimmt. Eine weitere Verallgemeinerung der ToA-Schätzung ergibt sich durch die Berücksichtigung eines komplexwertigen Pfadgewinns; es wird gezeigt, dass ein komplexwertiges Datenmodell ein entsprechendes reellwertiges Datenmodell um den Faktor $\frac{1}{4}$ im asymptotischen Fehlersinne übertrifft. Des Weiteren werden neue Algorithmen für die vorliegende Problemstellung vorgeschlagen und durch Berechnung der Cramer-Rao-Schranke eingehend analysiert.

Im zweiten Teil der Arbeit wird die Kapazität der Ultrabreitband-Kommunikation (UWB-Kommunikation) für einen standardisierten Kanal mit Cluster-Effekt abgeleitet und auf Mehrantennensysteme erweitert, wobei die Laufzeitverzögerungen der Antennenelemente mit berücksichtigt werden. Für unkorreliertes Fading sind die oberen Schranken sowie die Approximation der Kanalkapazität unabhängig von den Laufzeitverzögerungen der Antennenelemente. Die Kanalkapazität wächst zunächst mit der Anzahl der Pfade, um dann in eine Sättigung zu gehen. Die Kanalkapazität ist dann nahezu konstant und von der Anzahl der Pfade unabhängig. Darüber hinaus ist die Kanalkapazität der standardisierten NLoS-Kanalmodelle (Non-Line-of-Sight, NLoS) generell höher als die der standardisierten LoS-Kanalmodelle (Line-of-Sight, LoS).

Schlagworte: Parameterschätzung, Pfadverlust, Ultrabreitband.

ABSTRACT

This thesis deals with the localization and communication by means of radio signals. Based on the time-of-arrival (ToA), the first part of this thesis addresses the estimation of the position of a mobile station and the enhancement of the estimation accuracy. The second part of this thesis evaluates the channel capacity of the multiantenna ultrawideband communication channels in order to predict the achievable data rate.

In the first part, a classical ToA estimation approach is considered in conjunction with a path loss model. It is shown that the path loss exploitation increases the ToA estimation accuracy, provided that the path loss exponent (PLE) is perfectly known at the receiver. Apart from such prospect performance improvement, the performance of the geolocalization by exploiting the path attenuation information is also investigated when the PLE is not exactly known. It is found that for a small deterministic PLE error and a low signal-to-noise ratio, the maximum likelihood (ML) estimator can still benefit from the path loss model even when the path loss model is subject to the uncertain PLE. More precisely, the ML estimator under the imperfect PLE can provide lower root mean square error than the conventional maximum correlation estimator, which does not require any PLE knowledge. The above results, which are obtained for real-valued data models, is then extended to complex-valued data models. It is found that a special complex data model outperforms the real data model by a factor $\frac{1}{4}$ in terms of the asymptotic error variance. Applying the ToA estimation with the path gain attenuation information to the wireless non-line-of-sight (NLoS) geolocation problem, we analyze the Cramér-Rao bound of the mobile position estimation.

In the second part, the channel capacity is derived for a standard channel including cluster feature, which is further extended to the multiantenna systems taking into account the propagation delay across antenna elements. For uncorrelated fading, the upper bounds and the approximate channel capacity using the determinant approximation do not depend on the antenna element time delay. The channel capacity increases with the number of rays. However, it will be saturated when the number of rays becomes sufficiently large. In addition, the channel capacity of the standard NLoS channel models is higher than that of the standard line-of-sight channel models.

Keywords: Parameter estimation, path loss, ultrawideband.

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Bamrung Tau Sieskul
Hannover, im Juli 2010

To my family,
colleagues,
readers,
and those who may find it useful.

PUBLICATIONS

MAIN WORKS

Apart from the following publications, the contents of this thesis are drawn from some unpublished analyses and derivations.

Conferences

1. B. Tau Sieskul, F. Zheng, and T. Kaiser, "A hybrid SS-ToA wireless NLoS geolocation based on path attenuation: Mobile position estimation," *IEEE Wireless Communications & Networking Conference (WCNC)*, Budapest, Hungary, April 5-8, 2009, pp. 1-6.
2. B. Tau Sieskul, T. Kaiser, and F. Zheng, "A hybrid SS-ToA wireless NLoS geolocation based on path attenuation: Cramér-Rao bound," *IEEE 69th Vehicular Technology Conference (VTC2009-Spring)*, Barcelona, Spain, April 26-29, 2009, pp. 1-5.
3. B. Tau Sieskul, F. Zheng, and T. Kaiser, "Time-of-arrival estimation in path attenuation", *IEEE International Workshop on Signal Processing Advances for Wireless Communications (SPAWC)*, Perugia, Italy, June 21-24, 2009, pp. 573-577.
4. B. Tau Sieskul, C. Kupferschmidt, and T. Kaiser, "Algebraic inequalities for MIMO-UWB with antenna element time delays: Uncorrelated fading", *2009 IEEE International Conference on Ultra-Wideband (ICUWB 2009)*, Vancouver, Canada, September 9-11, 2009, pp. 798-803.

Journals

1. B. Tau Sieskul, F. Zheng and T. Kaiser, "On the effect of shadow fading on wireless geolocation in mixed LoS/NLoS environments," *IEEE Transactions on Signal Processing*, vol. 57, no. 11, pp. 4196-4208, Nov. 2009.
2. B. Tau Sieskul, F. Zheng and T. Kaiser, "A hybrid SS-ToA wireless NLoS geolocation based on path attenuation: ToA estimation and CRB for mobile position estimation," *IEEE Transactions on Vehicular Technology*, vol. 58, no. 9, pp. 4930-4942, Nov. 2009.

RELATED WORKS

Under the roles of participant, editor, supervisor, and author, several works, which vary from slight to high relation to the topics in this thesis, have been conducted as follows.

Technical Reports

1. T. Kaiser, M. El-Hadidy, E. Dimitrov, und B. Tau Sieskul, „Ultrawideband auf der Picatinny-Rail—Kapitel 3: Aspekte der Nachrichtenübertragungssysteme," Heckler&Koch-Projekt, Studie zum Thema Interoperabilität System Soldat (SF163), Leibniz Universität Hannover, Hannover, Jul. 2007.
2. M. Chiani, M. Fabbri, A. Giorgetti, C. Kupferschmidt, S. A. El Din, and B. Tausieskul, "Application-specific channel modeling with spatial and tempo-

ral correlation analysis of the theoretical limits of MIMO-UWB," Integrated Project - EUWB, Tech. Rep. Deliverable D3.1.3, Jan. 2009.

Supervised Theses

1. M. Saleem, "Channel capacity assessment for the UWB wireless communication system in the presence of lognormal fading", in partial fulfillment of the requirements for the degree of Master of Science (M.Sc.) in Computer Science and Communication Engineering, Fachgebiet Nachrichtentechnische Systeme (Department of Communication Systems), Universität Duisburg-Essen (University of Duisburg-Essen), Duisburg, Mar. 2006.
2. M. I. Valera Martínez "A hybrid SS-ToA wireless geolocation based on path attenuation: Robustness investigation under imperfect path loss exponent," supported in part by the European Region Action Scheme for the Mobility of University Students (ERASMUS) for performing the Master's thesis at the Leibniz University of Hannover, Germany, in partial fulfillment of the requirements for the degree of Telecommunications Engineer at the Technical University of Cartagena, Spain, Aug. 2009.

Conferences

1. B. Tau Sieskul and T. Kaiser, "Cramér-Rao bound for TOA estimations in UWB positioning systems," *IEEE International Conference on Ultra-Wideband (ICU)*, Zurich, Switzerland, Sep. 2005, pp. 408-413.
2. T. Kaiser and B. Tau Sieskul, "An Introduction to multiple antennas for UWB communication and localization," *Conference on Information Sciences and Systems (CISS)*, Princeton, NJ, March 2006, pp. 638-643.
3. M. Saleem, B. Tau Sieskul, and T. Kaiser, "Channel capacity assessments in UWB communication system over lognormal fading," *IEEE Symposium on Ultra Wideband Systems, Technologies and Applications*, London, UK, April, 2006, pp. 155-159.
4. T. Kaiser, C. Senger, and B. Tau Sieskul, "Antenna arrays for UWB indoor localization in non-line of sight environments," invited paper, *IEEE MTT-S International Microwave Symposium*, San Francisco, CA, June, 2006.
5. M. I. Valera Martínez, B. Tau Sieskul, F. Zheng, and T. Kaiser, "A hybrid SS-ToA wireless geolocation based on path attenuation under imperfect path loss exponent," *18th European Signal Processing Conference 2010 (EUSIPCO-2010)*, August 2010, accepted for presentation.
6. B. Tau Sieskul, C. Kupferschmidt, and T. Kaiser, "Spatial fading correlation for semicircular scattering: Angular spread and spatial frequency approximations," *3rd International Conference on Communications and Electronics 2010 (ICCE 2010)*, August 2010, accepted for presentation.

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1. T. Kaiser, C. Senger, J. Schroeder, S. Galler, E. Dimitrov, M. El-Hadidy and B. Tau Sieskul, "Ultra-wideband wireless systems: A broad review," *The Radio Science Bulletin*, no. 320, pp. 25-39, March, 2007.
2. B. Tau Sieskul, C. Kupferschmidt, and T. Kaiser, "Spatial fading correlation for local scattering: A condition of angular distribution," *IEEE Transactions on Vehicular Technology*, Feb. 2010, second revision.

Book Chapters

1. T. Kaiser, C. Senger, A. Eltaher, and B. Tau Sieskul, Localization in non-line-of-sight scenarios with ultra-wideband antenna arrays, in *Ultra Wideband: Antennas and Propagation for Communications, Radar and Imaging*, edited by B. Allen, M. Dohler, E. E. Okon, W. Q. Malik, A. K. Brown, and D. J. Edwards, John Wiley & Sons, 2007.
2. T. Kaiser, F. Zheng, B. Tau Sieskul, and K. Maichalernnukul, An Overview of UWB Systems with MIMO, in *Short-Range Wireless Communications Emerging Technologies and Applications*. Edited by R. Kraemer and M. D. Katz, ch. 9, pp. 65-72, John Wiley & Sons, 2009.
3. B. Tau Sieskul, F. Zheng, and T. Kaiser, Mobile Position Estimation Using Time of Arrival in Mixed LOS/NLOS Environments, in *Position Location - Theory, Practice and Advances: A Handbook for Engineers and Academics*. Edited by S. Zekavat and M. Buehrer, under review, 2010.

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NOMENCLATURE

AoA	angle of arrival
AoD	angle of departure
ACRB	asymptotic Cramér-Rao bound
AETD	antenna element time delay
BCML	bias-corrected maximum likelihood
BCRB	Bayesian Cramér-Rao bound
BS	base station
CDMA	Code Division Multiple Access
CM	channel model
CRB	Cramér-Rao bound
CSI	channel state information
DoA	direction of arrival
DS	direct sequence
EML	even maximum likelihood
FFT	fast Fourier transform
FIM	Fisher information matrix
IML	imperfect maximum likelihood
KL	Karhunen-Loève
LAN	local area network
LoS	line of sight
LLS	linearized least squares
LS	least squares
MC	maximum correlation
MCRB	modified Cramér-Rao bound
MFIM	modified Fisher information matrix
MIMO	multiple-input multiple-output
ML	maximum likelihood
MS	mobile station
MSE	mean square error
NLoS	non-line of sight
OFDM	orthogonal frequency division multiplexing
OML	odd maximum likelihood
PAM	pulse amplitude modulation

pdf	probability density function
PDP	power delay profile
PLE	path loss exponent
PPM	pulse position modulation
PSD	power spectral density
PSK	phase shift keying
QAM	quadrature amplitude modulation
QPSK	quadrature phase shift keying
RMS	root mean square
RMSE	root mean square error
SBCRB	simplified Bayesian Cramér-Rao bound
SNR	signal-to-noise ratio
SS	signal strength
TH	time hopping
ToA	time of arrival
TDoA	time difference of arrival
UWB	ultra-wideband
WLS	weighted least squares

LISTINGS

Some notations are described together with their first appearances as follows.

$\mathbf{1}_{B-M}$	column vector whose entries are B – M ones in (7.29)
α	amplitude or path gain in (1.1)
$\alpha[k, l]$	tap weight of the k-th component in the l-th cluster in (8.7)
α_b	path gain to the b-th BS in (5.5)
$\hat{\alpha}_{MC}$	MC estimate of the path gain in (3.35)
\mathbf{a}	vector of path gains from all multipath components in (1.12)
\mathbf{a}	vector of path gains from all BSs in (6.15)
\mathbf{a}	vector defined in (8.25a)
$\bar{\mathbf{a}}$	vector of LoS path gains in (6.18a)
$\hat{\mathbf{a}}_{ML}$	ML estimator of the path gains from all multipath components in (1.17)
\mathbf{A}	matrix defined in (8.26a)
$\mathbf{A}[k, l]$	matrix defined in (8.27a)
$\mathbf{A}(\hat{\rho})$	matrix defined in (7.25)
$\hat{\mathbf{A}}$	matrix defined in (7.34)
$\hat{\mathbf{A}}[k, l]$	dispersion matrix of the amplitude matrix in Sec. 8.7.1
b	index of the b-th BS in (5.1)
b_k	complex data symbol at the k-th sub-carrier in (2.39)
$b_{\tau\tau}$	CRB of the ToA estimation in (4.12)
$b_{\tau\tau \hat{\alpha}}$	CRB for unstructured complex-valued model in polar form in (4.26b)
$b_{\tau\tau \gamma}$	CRB for complex-valued path loss model with perfect PLE in (4.30)
$b_{\tau\tau \hat{\gamma}}$	CRB for complex-valued path loss model with unknown PLE in (4.32b)
B	number of BSs in (5.1)
\bar{B}_{\det}	determinant upper bound on channel capacity in (8.37)
\bar{B}_{Jensen}	Jensen upper bound on channel capacity in (8.36)
\bar{B}_{tr}	upper bound based on trace inequality in (8.41)
$\bar{B}_{\text{tr}+\text{Jensen}}$	upper bound based on trace and Jensen's inequalities in (8.41)
$\mathbf{B}[k, l]$	matrix defined in (8.33)
$\mathbf{B}_{\tau\tau}$	matrix of CRB on ToA error variances in (6.16)
\mathbf{B}_{pp}	matrix of CRB on position error variances in (6.17)
$\check{\mathbf{B}}_{pp}$	error covariance matrix by modified CRB in (7.52)
$\check{\check{\mathbf{B}}}_{pp}$	error covariance matrix by simplified Bayesian CRB in (7.56)
$\check{\mathbf{B}}_{pp}$	error covariance matrix by Bayesian CRB in (7.65)
$\bar{\mathbf{B}}_{pp}$	error covariance matrix by asymptotic CRB in (7.46)
c	speed of the light in (2.8)
c_1	constant defined in (4.61)
c_2	constant defined in (4.61)
c_3	constant defined in (4.61)
c_4	constant in (8.39)
C	channel capacity in (1.30)
\check{C}	ergodic capacity in Sec. 8.2.1
\check{C}	approximate channel capacity in (8.40)
$\check{C}_{\text{approdet}}$	approximate channel capacity after inserting the expectation in (8.40)
C	set of complex number
d	distance between the transmitter and the receiver in (2.8)
d	distance of adjacent antenna element separation in Sec. 8.4.1
d_0	close-in reference distance in (2.8)

$d_b[i]$	the i -th range measurement to the b -th station in (1.18)
\mathbf{d}_b	vector of the position of the b -th station in (1.22c)
$\tilde{\mathbf{d}}$	vector taken from the distances between $B - M$ LoS BSs and the MS
$\hat{\mathbf{d}}$	vector of distances between M NLoS BSs and the MS in (7.30a)
$\mathbf{D}(\cdot)$	diagonal matrix whose diagonal elements are given by the vector \cdot
\mathbf{e}_b	error vector in (1.22e)
E	received energy
E_b	received energy at the b -th BS in (5.2)
E_h	channel energy related to (1.35)
E_s	transmitted energy from the mobile station in (5.2)
E_{ss}	the energy of the signal in (2.2)
$E_{ss}(\tau)$	exact signal energy as a function of the ToA in (4.6)
$\dot{E}_{ss}(\tau)$	correlation between the transmitted signal and its derivative in (4.7)
$\ddot{E}_{ss}(\tau)$	correlation between the derivatives of the transmitted signal in (4.8)
$\dot{E}_{s_R s_R}(\tau_0)$	correlation between the derivatives of the real parts of signal in (4.13a)
$\dot{E}_{s_I s_I}(\tau_0)$	correlation between the derivatives of the imaginary parts of signal in (4.13b)
$E_{s_R s_R}(\tau_0)$	correlation between the real parts of signal in (4.13c)
$E_{s_I s_I}(\tau_0)$	correlation between the imaginary parts of signal in (4.13d)
$\dot{E}_{s_R \dot{s}_R}(\tau_0)$	correlation between real part and its derivative in (4.13e)
$\dot{E}_{s_I \dot{s}_I}(\tau_0)$	correlation between imaginary part and the derivative of real part in (4.13f)
$E_{s_R \dot{s}_I}(\tau_0)$	correlation between real part and the derivative of imaginary part in (4.13g)
$\dot{E}_{s_I \dot{s}_I}(\tau_0)$	correlation between imaginary part and its derivative in (4.13h)
$\check{E}_{ss}(\tau)$	signal energy defined in (4.47a)
$\check{\check{E}}_{ss}(\tau)$	signal energy defined in (4.47b)
$\check{\check{\check{E}}}_{ss}(\tau)$	signal energy defined in (4.47c)
$\check{\check{\check{\check{E}}}}_{ss}(\tau)$	signal energy defined in (4.47d)
$E_{ss}(\tau, \hat{\tau})$	signal energy defined in (1.16b)
$\mathbf{E}_{ss}(\boldsymbol{\tau}, \boldsymbol{\tau})$	matrix of signal correlations in (1.15b)
f_0	central frequency in (2.8)
$f_{b,k}(t)$	orthonormal function at the b -th BS in (5.10)
f_k	central frequency in (2.39)
$f_k(t)$	orthonormal function in (2.14)
f_H	highest frequency of signal which is at least 10 dB below the peak in Sec. 1.1.1
f_L	lowest frequency of signal which is at least 10 dB below the peak in Sec. 1.1.1
$f_{ML}(\boldsymbol{\eta})$	ML objective as a function of $\boldsymbol{\eta}$ in (4.23)
$f_{ML}(\tau \gamma)$	ML function written as a function of τ conditioned on γ in (3.1)
$g(\xi, \omega)$	quantity defined in (7.64b)
$g_\xi(\xi)$	quantity defined in (7.64a)
$h(t)$	channel impulse response in (8.7)
$h(\xi, \omega)$	quantity defined in (7.63b)
$h_{\sigma_n^2 \sigma_n^2}$	Fisher information of noise variance in (4.20)

$h_{\tau \hat{\alpha}}$	Fisher information in (4.27)
$h_{\xi}(\xi)$	quantity defined in (7.63a)
$h_{n_r, n_t}^{k,l}$	channel of AETD in (8.20)
$h_{n_r, n_t}(t)$	effective channel impulse response in (8.22)
$\tilde{h}_{\xi, \xi}$	modified Fisher information of ξ in (7.55)
$\tilde{h}_{\xi, \xi}$	quantity defined in (7.62)
$\tilde{\mathbf{H}}_{\tau, \xi}$	modified Fisher information vector for NLoS in Sec. 7.4.3
$\tilde{\mathbf{H}}_{\tau, \xi}$	modified Fisher information vector for LoS in Sec. 7.4.3
$\mathbf{H}(t)$	MIMO channel matrix in (8.1)
$\mathbf{H}_{K,L}(f)$	channel matrix in frequency domain with $K + 1$ clusters and $L + 1$ rays in (8.32)
$\mathbf{H}_{\tilde{L}}(f)$	Fourier transform of the channel matrix in (8.3)
\mathbf{H}_{uu}	Fisher information matrix in (7.47)
$\mathbf{H}_{\tau\tau}$	Fisher information matrix in (6.14)
$\mathbf{H}_{\theta\theta}$	Fisher information matrix in (4.17)
$\check{\mathbf{H}}_{\theta\theta}$	total information matrix in (7.59)
$\bar{\mathbf{H}}_{uu}$	modified FIM in (7.49)
$\bar{\mathbf{H}}_{\theta\theta}$	modified FIM of model parameter in 7.54
$\tilde{\mathbf{H}}_{\tau\tau}$	modified FIM for NLoS ToAs in (7.51a)
$\bar{\mathbf{H}}_{\tau\tau}$	modified FIM for LoS ToAs in (7.51b)
$\tilde{\mathbf{H}}_{\theta\theta}$	<i>a priori</i> information matrix in (7.59)
$I_0(x)$	zeroth order modified Bessel functions of the first kind in (4.48a)
$I_k(x)$	k -th order modified Bessel functions of the first kind in (4.48a)
$\mathbf{I}(\cdot)$	identity matrix of size \cdot in (8.2)
k_1	constant defined in (4.61)
k_m	mean factor defined in (8.10a)
k_γ	parameter describing the increase in the decay constant with the delay in (8.18)
\tilde{k}_m	standard deviation factor defined in (8.10b)
K	$K + 1$ is the number of rays in (8.7)
$l(\tau r(t); t \in (0, T_0])$	likelihood function in logarithm scale in (2.20)
l_b	additional path length caused by the NLoS propagation in (5.3)
$l(\tau_b r_b(t); t \in (0, T_0])$	likelihood function in logarithm scale in (5.16)
$l_{n,m}(\mathbf{y})$	likelihood ratio in (1.37)
\mathbf{l}	vector of additional path lengths caused by NLoS propagation in (5.7)
L	$L + 1$ is the number of clusters in (8.7)
\bar{L}	mean of L in (8.8)
\tilde{L}	number of multipath components in Theorem 3
m	m -factor of Nakagami distribution in (8.9)
M	number of BSs that are subject to the NLoS propagation
M	large number for approximating the infinite sum in Sec. 8.9
M_c	shadowing exponent in (8.19)
$\mathbf{M}(f)$	matrix defined in (8.3)
n	index of sampling point in (7.14)
$n(t)$	additive noise at the receiver at time t in (1.1)

$n_b(t)$	additive noise at the b -th BS in (5.5)
$n_{b,k}$	noise sample at the b -th BS in (5.13)
$n_I(t)$	imaginary part of the noise $n(t)$ in (4.10f)
n_k	noise sample in (2.18b)
n_p	index of multipath component in (1.7)
n_r	index of antenna element at the receiver in Sec. 8.4.1
$n_R(t)$	real part of the noise $n(t)$ in (4.10e)
n_t	index of antenna element at the transmitter in Sec. 8.4.1
$\mathbf{n}(t)$	additive noise at the receiver in (8.1)
N	the number of measurements in (1.18)
N	number of complex data symbols per block in (2.39)
N_0	double-sided power spectral density
N_o	number of observed samples after sampling in (7.14)
N_p	number of multipath components in (1.7).
N_r	number of antenna elements at the receiver in Sec. 8.2
N_s	number of samples at which the transmitted signal is nonzero in (7.16)
N_t	number of antenna elements at the transmitter in Sec. 8.2
\tilde{N}	number of random parameters in Sec. 8.2.1
\tilde{N}	minimum number between the numbers of the transmitter and receiver antennas in (8.2)
\mathcal{N}	set of BS indices that are subject to the NLoS propagation
$o(\cdot)$	little 'o' of Bachmann-Landau symbols in (2.21)
$O(\cdot)$	big 'O' of Bachmann-Landau symbols in (8.38)
Ω	mean square value of the amplitude in (8.9)
$p(r_1, \dots, r_K \tau)$	conditional pdf of the received signal samples in (2.19)
$p(r_{b,1}, \dots, r_{b,K} \tau_b)$	conditional pdf of received signal samples at the b -th BS in (5.15)
$p_{r \mathbf{u}}(\mathbf{r} \mathbf{u})$	marginal pdf in (7.48)
$p_{r \mathbf{v},\mathbf{u}}(\mathbf{r} \mathbf{v},\mathbf{u})$	conditional pdf in (7.48)
$p_{\mathbf{v}}(\mathbf{v})$	pdf of \mathbf{v} in (7.48)
$p(\mathbf{x}, \mathbf{y})$	joint pdf of \mathbf{x} and \mathbf{y} in (1.36)
\mathbf{p}	position of the MS in (5.7)
\mathbf{p}_b	the b -th BS position in (5.1)
$\hat{\mathbf{p}}_{LS}$	position estimate using the LS criterion in (6.8)
$\hat{\mathbf{p}}_{ML}$	position estimate using the ML criterion in (6.10)
$\hat{\mathbf{p}}_{WLS}$	position estimate using the WLS criterion in (6.9)
$\check{\mathbf{p}}$	a guessed value of the true position in Sec. 1.1.2
P	limited power for transmission in (8.5)
\mathbf{P}	matrix of all BS positions in (5.30)
$\hat{\mathbf{q}}_{LLS}$	vector defined in (1.27)
$Q(\cdot)$	transition probability function related to (1.35)
r	cell radius in (5.30)
$r(t)$	received signal at time t in (2.9)
$r_b(t)$	received signal at the b -th BS in (5.5)
$r_{b,k}$	received signal sample at the b -th BS in (5.12)

$r_I(t)$	imaginary part of the received signal $r(t)$ in (4.10b)
r_k	received signal sample in (2.16)
$r_R(t)$	real part of the received signal $r(t)$ in (4.10a)
$r(t)$	vector of received signals from all BSs in (5.17)
\mathbb{R}_+	set of positive number
$R(f)$	Fourier transform of $r(t)$ in (2.43)
$\mathbf{R}_{nn}(\tau)$	noise autocovariance matrix in (8.28)
$\mathbf{R}_{xx}(\tau)$	transmitted signal autocovariance matrix in (8.30)
$s(t)$	transmitted signal in (2.1)
$s_{b,k}$	signal sample at the b -th BS in (5.13)
$s_I(t)$	imaginary part of the transmitted signal $s(t)$ in (4.10d)
s_k	signal sample in (2.18a)
$s_R(t)$	real part of the transmitted signal $s(t)$ in (4.10c)
$\dot{s}(t)$	derivative of the signal $s(t)$ with respect to the time t in (1.6)
$\mathbf{s}(t, \boldsymbol{\tau})$	vector of delayed transmitted signals in (7.8c)
$\tilde{\mathbf{s}}(t; \boldsymbol{\tau}, \xi)$	composite signal defined in (7.20)
$\tilde{s}(t)$	OFDM signal in (2.39)
$S(f)$	Fourier transform of the transmitted signal $s(t)$ in (2.6)
SNR	SNR in (1.4)
SNR_{dB}	SNR in decibel in (2.42)
$\overline{\text{SNR}}_b$	received SNR at the b -th BS
t	time on the real line
$T[l]$	the l -th cluster arrival time in (8.7)
T_s	signal duration in Sec. 1.1.2
T_o	observation period in (2.2)
T_f	frame period (1.35)
u	Gaussian random variable only in (7.40)
\mathbf{u}	deterministic parameter in Sec. 7.4.2
v	Gaussian random variable only in (7.41)
\mathbf{v}	random parameter in Sec. 7.4.2
$w(t)$	signal waveform in (2.1)
W	bandwidth in Sec. 1.1.1
$\tilde{\mathbf{W}}$	weighting matrix corresponding to LoS portion in (6.9)
x	x coordinate of the MS in x - y plane in (5.8)
x_0	true value of x in (5.22)
x_b	x coordinate of the b -th BS in x - y plane in (5.1)
\tilde{x}_b	relative distance in the x -axis between the b -th BS and the MS in (5.3)
$x(t)$	transmitted signal at the transmitter in (8.1)
y	y coordinate of the MS in x - y plane in (5.8)
y_0	true value of y in (5.22)
y_b	y coordinate of the b -th BS in x - y plane in (5.1)
\tilde{y}_b	relative distance in the y -axis between the b -th BS and the MS in (5.3)
$y(t)$	received signal at the receiver in (8.1)
α	amplitude of complex path gain in (4.18)
α_b	quantity defined in (5.28)

α_b	real path gain with shadow fading in (7.6)
$\alpha_{n_r, n_t}[k, l]$	antenna-dependent complex amplitude in (8.23)
$\boldsymbol{\alpha}$	vector of path gains from all BSs in (7.8b)
β	effective bandwidth in (1.5)
β	frequency band
β	mixture probability parameter in (8.14)
$\bar{\beta}$	Gabor's effective bandwidth in (2.6)
$\bar{\beta}_c$	critical effective bandwidth in (7.31)
χ_b	quantity defined in (5.24a)
χ	attenuation factor of the first component in (8.15)
δ	Nyquist sampling period in (7.14)
$\delta(t)$	Dirac delta function in (8.7)
$\delta_{\cdot, \cdot}$	Kronecker delta function
(δ_x, δ_y)	the corresponding guessed error pair in Sec. 1.1.2
δ_γ	PLE error in (3.6)
$\check{\delta}_\gamma$	upper limit of the confident PLE difference in (3.20)
$\boldsymbol{\delta}$	vector defined in (8.25e)
$\hat{\boldsymbol{\delta}}_{LLS}$	linearized least squares estimate in (1.23)
$\boldsymbol{\Delta}$	matrix defined in (1.22a)
ϵ	ratio of total positioning errors in (7.39)
$\epsilon(\tau \gamma)$	bias in parametric form in (3.32)
$\bar{\epsilon}$	statistical mean of ϵ in (7.43)
$\bar{\epsilon}$	empirical error variance in (6.22)
ϵ^2	total positioning accuracy in (5.22)
η_b	delay in discrete time in (7.16)
$\boldsymbol{\eta}$	vector of random parameters in Sec. 8.2.1
$\hat{\boldsymbol{\eta}}_{ML}$	ML estimate of $\boldsymbol{\eta}$ in (4.22)
γ	path loss exponent
γ_0	true value of the PLE in (2.25)
γ_1	parameter determining the decay at later times in (8.15)
γ_b	PLE at the b -th BS in (5.2)
γ_{max}	maximum value of the truncated random PLE in (3.23)
γ_{min}	minimum value of the truncated random PLE in (3.23)
$\gamma_{MC}(\tau)$	PLE estimate based on the MC estimator in (3.33)
γ_r	parameter determining how fast the PDP increases to its local maximum in (8.15)
γ_t	mean of the truncated Gaussian PLE in (3.24)
$\bar{\gamma}$	mean of the untruncated random PLE in (3.23)
$\hat{\gamma}_{MC}$	PLE estimate using the MC estimator in (3.36)
$\hat{\gamma}_{ML}$	PLE estimate using the ML estimator in (3.3)
$\bar{\gamma}_t$	mean of the truncated Gaussian PLE in (3.28)
$\check{\gamma}_0$	root for a condition of γ_0 in (3.31)
$\gamma[l]$	intra-cluster decay time constant in (8.15)
$\boldsymbol{\gamma}$	vector of the PLEs from all BSs in (6.6b)
$\bar{\boldsymbol{\gamma}}$	vector of LoS PLEs in (6.18b)
$\Gamma(\cdot)$	gamma function in (8.9)

ι	sign of the amplitude in (8.11)
κ	constant depending on antenna characteristics and average channel attenuation in (2.8)
κ_{dB}	constant κ in decibel in (2.42)
λ_1	a ray arrival rate in (8.14)
λ_2	another ray arrival rate in (8.14)
$\lambda_{b,k}$	eigenvalue of homogeneous Fredholm integral at the b -th BS in (5.10)
λ_k	eigenvalue of homogeneous Fredholm integral in (2.14)
$\Lambda[l]$	cluster arrival rate in (8.13)
μ_0	mean factor defined in (8.10a)
$\mu_m(\tau)$	mean of lognormal random variable in (8.10a)
μ_σ	mean of σ in (7.41)
$\tilde{\mu}_0$	standard deviation factor defined in (8.10a)
ν	constant in (7.37)
$\Omega[l]$	energy of the l -th cluster in (8.15)
ϕ	phase shift of complex path gain in (4.18)
ϕ	AoA in Sec. 8.4.1
ϕ_b	relative angle between the b -th BS and the MS in (5.24b)
Φ	vector of relative angles in (5.32)
Φ	vector defined in (8.25c)
$\Phi(\cdot)$	normal cumulative distribution function in (3.27)
Φ	matrix defined in (8.26c)
$\Phi[k, l]$	matrix defined in (8.27c)
Φ_{xx}	limited PSD matrix of a certain regulation in (8.6)
$\bar{\Phi}$	matrix taken from the last $B - M$ columns of Φ in (6.4)
$\psi_{n_r, n_t}[k, l]$	propagation delay across antenna element in (8.20)
$\Psi(\tilde{\rho})$	matrix defined in (7.28)
ρ	average SNR related to (1.35)
σ	standard deviation of $\tilde{\sigma}$ in (7.40)
$\sigma \sim \mathcal{N}(\mu_\sigma, \sigma_\sigma^2)$	σ is distributed as real Gaussian random variable with mean μ_σ and variance σ_σ^2
$\sigma \sim \mathcal{N}_{\gamma_{\min}}^{\gamma_{\max}}(\mu_\sigma, \sigma_\sigma^2)$	σ is distributed as real truncated Gaussian random variable with untruncated mean μ_σ and untruncated variance σ_σ^2 within $[\gamma_{\min}, \gamma_{\max}]$
$\Pi_{xx}(f)$	Fourier transform of the transmitted signal correlation matrix in (1.38)
$\Pi_{nn}(f)$	Fourier transform of the noise covariance matrix in (1.38)
$\rho_{ns}(\tau)$	correlation between the noise and the transmitted signal in (2.35)
$\rho_{ns}(\tau)$	correlation between the noise and the derivative of the transmitted signal in (2.25)
$\rho_{rs}(\tau)$	correlation between the received signal and the transmitted signal delayed with τ in (2.23)
$\tilde{\rho}$	quantity defined in (7.29)
$\check{\rho}$	quantity defined in (7.57)
$\tilde{\rho}$	quantity defined in (7.66)
$\rho_{rs}(\tau)$	vector of the correlations in (1.15a)
$\tilde{\sigma}$	shadowing exponent in (7.37)

σ_c	standard deviation of shadowing exponent in (8.19)
σ_σ	standard deviation of σ in (7.41)
σ_∞	infinite summation of PDP in (8.45)
$\check{\sigma}_{1,1}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{1,2}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{1,3}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{1,4}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{2,2}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{2,3}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{2,4}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{3,3}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{3,4}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{4,4}$	an element of $\check{\Sigma}^{-1}$ in (4.58)
$\check{\sigma}_{1 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{2 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{4 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{1,2 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{1,4 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{2,4 3}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{1 4}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{2 4}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{3 4}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{1,2 4}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{1,3 4}(\tau_0)$	a quantity defined in (4.59)
$\check{\sigma}_{2,3 4}(\tau_0)$	a quantity defined in (4.59)
σ_b^2	error variance of ToA from the b-th BS in (6.6c)
σ_n^2	the variance of the noise sample in (2.19)
σ_γ^2	variance of the random PLE in (3.22)
$\sigma_{\gamma_t}^2$	variance of the truncated Gaussian PLE in (3.25)
$\check{\sigma}_{\gamma_t}^2$	variance of the truncated Gaussian PLE in (3.29)
$\hat{\sigma}_n^2$	estimate of noise variance in (4.20)
σ^2	vector the ToA error variances taken from all LoS BSs in (6.6c)
$\Sigma_{AA}[k, l, \check{k}, \check{l}]$	covariance matrix of the amplitude matrix in (8.42)
$\Sigma_{nn}(f)$	PSD matrix of the additive noise in (8.3)
$\Sigma_{xx}(f)$	PSD matrix of the transmitted signal in (8.2)
$\check{\Sigma}$	matrix defined in (4.57)
τ	time delay in (1.1)
$\tau[k, l]$	the delay of the k-th multipath component relative to the l-th cluster arrival time $T[l]$ in (8.7)
τ_0	true value of the ToA in (2.25)
τ_b	ToA at the b-th BS in (5.3)
$\hat{\tau}_{BCML}(\gamma)$	parametric estimate of the ToA using the BCML estimator in (3.37)
$\hat{\tau}_{EML}$	ToA estimate using the even ML estimator in (4.29)
$\hat{\tau}_{MC}$	ToA estimate using the MC estimator in (2.24)

$\hat{\boldsymbol{\tau}}_{\text{ML}}$	ToA estimate using the ML estimator in (1.2)
$\hat{\boldsymbol{\tau}}_{\text{OML}}$	ToA estimate using the odd ML estimator in (4.29)
$\boldsymbol{\tau}_{n_p}$	ToA of the n_p -th multipath component in (1.7)
$\boldsymbol{\tau}$	vector of ToAs in (5.19)
$\bar{\boldsymbol{\tau}}$	vector taken from the last $B - M$ elements of $\boldsymbol{\tau}$ in (6.3)
$\hat{\boldsymbol{\tau}}$	estimate of $\boldsymbol{\tau}$ in (6.7)
$\hat{\bar{\boldsymbol{\tau}}}$	estimate of $\bar{\boldsymbol{\tau}}$ in (6.7)
θ	AoD in Sec. 8.4.1
$\boldsymbol{\theta}$	unknown parameter in (4.11)
$\boldsymbol{\theta}$	vector defined in (8.25d)
$\boldsymbol{\theta}_0$	true value of model parameter in (5.20)
$\boldsymbol{\theta}_{\alpha}$	unknown parameter for complex-valued unstructured model in (4.25)
$\boldsymbol{\theta}_{\gamma}$	unknown parameter in complex-valued path loss model in (4.28)
$\boldsymbol{\theta}_{\tilde{\gamma}}$	unknown parameter for complex-valued path loss in (4.31)
$\hat{\boldsymbol{\tau}}_{\text{ML}}$	ML estimate of the ToA from all multipath components in (1.14)
$\boldsymbol{\Theta}$	matrix defined in (8.26d)
$\boldsymbol{\Theta}[k, l]$	matrix defined in (8.27d)
$\nu[k, l]$	phase shift of the k -th component in the l -th cluster in (8.7)
\mathbf{v}	vector defined in (8.25b)
$\boldsymbol{\Upsilon}$	matrix defined in (1.26a)
$\boldsymbol{\Upsilon}$	matrix defined in (8.26b)
$\boldsymbol{\Upsilon}[k, l]$	matrix defined in (8.27b)
$\varepsilon_1(\boldsymbol{\tau}_0, \gamma_0)$	a quantity defined in (4.46a)
$\varepsilon_2(\boldsymbol{\tau}_0)$	a quantity defined in (4.46b)
$\varepsilon_{\text{CRB}}(\boldsymbol{\sigma})$	total error in both axes by CRB in (7.38)
$\varepsilon_{\text{ACRB}}$	estimation error of the mobile position from both axes by ACRB in (7.67a)
$\varepsilon_{\text{BCRB}}$	estimation error of the mobile position from both axes by SBCRB in (7.67c)
$\varepsilon_{\text{SBCRB}}$	estimation error of the mobile position from both axes by SBCRB in (7.67b)
ω	quantity defined in (7.45)
$\varphi_i(t)$	orthonormal basis function in (1.31)
$\varphi(t, \hat{t})$	eigenfunction, which is noise autocovariance function, in (2.14)
$\varphi_b(t, \hat{t})$	eigenfunction at the b -th BS in (5.10)
$\Xi(f)$	Fourier transform of the channel matrix in (1.38)
$\boldsymbol{\zeta}$	vector defined in (1.26c)
$\hat{\mathbf{q}}_{\text{LLS}}$	linearized least squares estimate in (1.27)
ξ_b	shadow fading at the b -th BS in (7.1)
$\tilde{\xi}$	random shadow fading in (7.37)
$\zeta(\boldsymbol{\tau})$	ML objective function in (2.31)
\simeq	approximation by neglecting $\text{o}(\cdot)$ in (2.22)
$*$	convolution in (8.1)
\odot	Hadamard product in (7.7)
$\frac{\partial}{\partial \mathbf{t}}$	partial derivative with respect to \mathbf{t}
$\ \cdot\ _{\text{E}}$	Euclidean norm

$(\cdot)^*$	complex conjugate of \cdot
$ \cdot $	absolute value of scalar \cdot , or determinant of matrix \cdot
$\lfloor \cdot \rfloor$	least integer number of \cdot
$(\cdot)^{-1}$	inverse of matrix \cdot
$\mathbf{B} \succeq \mathbf{C}$	difference matrix $\mathbf{A} = \mathbf{B} - \mathbf{C}$ is positive semidefinite
$\arg \max_{\tau} f(\tau)$	argument τ , which maximizes the objective function $f(\tau)$, in (2.24)
$\arg \min_{\tau} f(\tau)$	argument τ , which minimizes the objective function $f(\tau)$, in (2.33)
$\arg \text{zero}_{\tau} f(\tau)$	argument τ , which makes the objective function $f(\tau)$ zero, in (3.31)
$E_{n(\cdot)}\{\cdot\}$	expectation with respect to the realization of $n(\cdot)$ in (2.28)
$\text{erf}(\cdot)$	error function in (3.23)
$f(x) _{x=x_0}$	function $f(x)$ evaluated at $x = x_0$
$I_0(\cdot)$	zeroth order modified Bessel function of the first kind in (4.48a)
$I_k(\cdot)$	k -th order modified Bessel function of the first kind in (4.48b)
$\Im(\cdot)$	imaginary part of \cdot
$\ln(\cdot)$	natural logarithm function in (3.9)
$\log_{10}(\cdot)$	logarithm of base 10
$\max_x f(x)$	maximum value of the function $f(x)$ over the set of x in (8.2)
$[\mathbf{M}]_{[2 \times 2]}$	the first 2×2 block of \mathbf{M}
$\Re(\cdot)$	real part of \cdot
$\text{sinc}(\cdot)$	unnormalized sine cardinal function in (2.40)
$\text{tr}(\cdot)$	trace of matrix \cdot
$\text{vec}(\cdot)$	column-stacking vectorization in (8.25)